

$$x = x^1 e_1 + x^2 e_2 + \dots + x^n e_n \quad e_i \cdot e_j = \delta_{ij}$$

$$\xi = \xi^1 e_1 + \xi^2 e_2 + \dots + \xi^n e_n$$

$$j = \frac{\partial x^i}{\partial \xi^j} = \begin{pmatrix} \frac{\partial x^1}{\partial \xi^1} & \frac{\partial x^1}{\partial \xi^2} & \dots & \frac{\partial x^1}{\partial \xi^n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial x^i}{\partial \xi^1} & \dots & \dots & \frac{\partial x^i}{\partial \xi^n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial x^n}{\partial \xi^1} & \dots & \dots & \frac{\partial x^n}{\partial \xi^n} \end{pmatrix}$$

$$J = \det(j)$$

$$x^1 = x^1(\xi^1, \xi^2, \dots, \xi^n) \quad \xi^1 = \xi^1(x^1, \dots, x^n)$$

$$\vdots$$

similarly

$$\vdots$$

$$x^n = x^n(\xi^1, \xi^2, \dots, \xi^n) \quad \xi^n = \xi^n(x^1, \dots, x^n)$$

$$\therefore jj^T = I \quad \therefore \frac{\partial x^i}{\partial \xi^k} \frac{\partial x^k}{\partial \xi^j} = \frac{\partial x^i}{\partial \xi^j} = \delta_{ij}, \text{ similarly } \frac{\partial \xi^i}{\partial x^k} \frac{\partial x^k}{\partial \xi^j} = \delta_{ij}$$

$$x(\xi) = x^1(\xi) e_1 + \dots + x^n(\xi) e_n$$

Tangential vector:

$$\frac{\partial x}{\partial \xi^i} = \frac{\partial x^1}{\partial \xi^i} e_1 + \dots + \frac{\partial x^n}{\partial \xi^i} e_n$$

$$\partial \xi^i = \frac{\partial \xi^1}{\partial x^i} e_1 + \dots + \frac{\partial \xi^n}{\partial x^i} e_n$$

$$\therefore jj^T = I, \quad \therefore \frac{\partial x}{\partial \xi^i} \cdot \partial \xi^j = \delta_{ij}$$

$$\text{in 3D, } J = x_{y1} - (x_{y2} \times x_{y3}) \Rightarrow \partial \xi^i = \frac{1}{J} (x_{y2} \times x_{y3})$$

$$\frac{1}{J} = \partial \xi^1 \cdot (\partial \xi^2 \times \partial \xi^3) \Leftarrow x_{y1} = J (\partial \xi^2 \times \partial \xi^3)$$

let $b = \bar{b}^1 x_{\xi^1} + \dots + \bar{b}^n x_{\xi^n}$

$\rightarrow b \cdot \partial \xi^i = \bar{b}^i$ — covariant

Cartesian

$b = \bar{b}_1 \partial \xi^1 + \dots + \bar{b}_n \partial \xi^n$

$b \cdot x_{\xi^i} = \bar{b}_i$

Metric Tensors

$g_{ij} = \frac{\partial x}{\partial \xi^i} \cdot \frac{\partial x}{\partial \xi^j}$

$g_{ij} g^{jk} = \delta_i^k$

$g = j j^T$

$\det(g) = J^2$

$j^{-1} = \frac{1}{J} \begin{pmatrix} j_{11} & \dots & j_{1n} \\ \dots & \dots & \dots \\ j_{n1} & \dots & j_{nn} \end{pmatrix}^T$ j_{ij} is cofactor of j_{ij} (adjoint)

$\frac{\partial \xi^i}{\partial x^j} = \frac{1}{J} \left(\frac{\partial x^{j+1}}{\partial \xi^{i+1}} \frac{\partial x^{i+2}}{\partial \xi^{j+2}} - \frac{\partial x^{j+1}}{\partial \xi^{i+2}} \frac{\partial x^{i+2}}{\partial \xi^{j+1}} \right)$ for 3D

$\frac{\partial x^i}{\partial \xi^j} = J \left(\frac{\partial \xi^{j+1}}{\partial x^{i+1}} \frac{\partial \xi^{i+2}}{\partial x^{j+2}} - \frac{\partial \xi^{j+1}}{\partial x^{i+2}} \frac{\partial \xi^{i+2}}{\partial x^{j+1}} \right)$

$\frac{\partial \xi^i}{\partial x^j} = \frac{1}{J} (-1)^{i+j} \frac{\partial x^{3-j}}{\partial \xi^{3-i}}$ for 2D

$\frac{\partial x^i}{\partial \xi^j} = J (-1)^{i+j} \frac{\partial \xi^{3-j}}{\partial x^{3-i}}$

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Christoffel Symbols

$$x_{\xi^i} x_{\xi^j} = \Gamma_{ij}^k x_{\xi^k}$$

$$\Downarrow$$

$$\Gamma_{ij}^k = x_{\xi^i} x_{\xi^j} - \nabla \xi^k = \frac{\partial^2 x^l}{\partial \xi^i \partial \xi^j} \frac{\partial \xi^k}{\partial x^l}$$

$$x_{\xi^i} x_{\xi^j} = [i, j, k] \nabla \xi^k$$

$$\therefore [i, j, k] = x_{\xi^i} x_{\xi^j} - x_{\xi^k} = \frac{\partial^2 x^l}{\partial \xi^i \partial \xi^j} \frac{\partial x^l}{\partial \xi^k}$$

$$\cancel{[i, j, k]} g^mk = \frac{\partial^2 x^l}{\partial \xi^i \partial \xi^j} \frac{\partial x^l}{\partial \xi^k} \frac{\partial \xi^m}{\partial x^l} \frac{\partial x^l}{\partial \xi^m}$$

$$= \frac{\partial^2 x^l}{\partial \xi^i \partial \xi^j} \frac{\partial \xi^m}{\partial x^l}$$

$$= \Gamma_{ij}^m$$

$$[i, j, k] = \frac{\partial}{\partial \xi^i} \left(\frac{\partial x^l}{\partial \xi^j} \frac{\partial x^l}{\partial \xi^k} \right) - \frac{\partial x^l}{\partial \xi^i} \frac{\partial}{\partial \xi^j} \left(\frac{\partial x^l}{\partial \xi^k} \right)$$

$$= \frac{\partial}{\partial \xi^i} (g_{jk}) - \frac{\partial x^l}{\partial \xi^i} \frac{\partial}{\partial \xi^j} \left(\frac{\partial x^l}{\partial \xi^k} \right)$$

$$[i, j, k] = \frac{\partial}{\partial \xi^i} (g_{jk}) - \frac{\partial x^l}{\partial \xi^i} \frac{\partial}{\partial \xi^j} \left(\frac{\partial x^l}{\partial \xi^k} \right) \rightarrow \frac{\partial}{\partial \xi^i} \left(\frac{\partial x^l}{\partial \xi^j} \frac{\partial x^l}{\partial \xi^k} \right)$$

$$\therefore [i, j, k] = \frac{1}{2} \left(\frac{\partial g_{jk}}{\partial \xi^i} + \frac{\partial g_{ji}}{\partial \xi^i} - \frac{\partial g_{ij}}{\partial \xi^k} \right)$$

$$\Gamma_{ij}^k = \frac{1}{2} g^{km} \left(\frac{\partial g_{im}}{\partial \xi^j} + \frac{\partial g_{jm}}{\partial \xi^i} - \frac{\partial g_{ij}}{\partial \xi^m} \right)$$

Jacobian

$A = (a_{ij})$, $i, j = 1, \dots, n$, $a_{ij} = a_{ij}(x)$

$\det(A) = \sum_j a_{ij} G_{ij}$, G is cofactor

= ~~Ability~~ $\sum_i a_{i1} a_{i2} \dots a_{in}$

$\frac{d}{dx} \det(A) = \frac{da_{ij}}{dx} G_{ij}$

$J = \frac{\partial x^1}{\partial \xi^1} G^{11} + \frac{\partial x^2}{\partial \xi^1} G^{21} + \dots + \frac{\partial x^n}{\partial \xi^1} G^{n1}$ $\times \frac{\partial \xi^1}{\partial x^i}$

$0 = \frac{\partial x^1}{\partial \xi^2} G^{11} + \frac{\partial x^2}{\partial \xi^2} G^{21} + \dots + \frac{\partial x^n}{\partial \xi^2} G^{n1}$ $\times \frac{\partial \xi^2}{\partial x^i}$

\vdots

(summation)

$\frac{\partial \xi^1}{\partial x^i} J = G^{11}$

$\therefore G^{11} = J \frac{\partial \xi^1}{\partial x^i}$

$\frac{\partial \xi^i}{\partial x^j} = \frac{\partial x^k}{\partial \xi^i} \left| \frac{d(\frac{\partial x^k}{\partial \xi^i})}{dx^j} \right| \neq 0$, $\xi = x^k$
 $\neq 0$, $\xi \neq 0$

$\therefore \frac{\partial J}{\partial \xi^k} = J \frac{\partial x^l}{\partial \xi^k} \frac{\partial \xi^m}{\partial x^l} \frac{\partial \xi^m}{\partial x^k} = J \frac{d}{dx^k} \left(\frac{\partial x^l}{\partial \xi^k} \right) = J D \cdot \frac{\partial x^l}{\partial \xi^k}$

$\frac{d}{d\xi^j} \left(J \frac{\partial \xi^i}{\partial x^i} \right) = \frac{\partial J}{\partial \xi^j} \frac{\partial \xi^i}{\partial x^i} + J \frac{\partial^2 \xi^i}{\partial x^k \partial x^i} \frac{\partial x^k}{\partial \xi^j}$

$= J \frac{\partial x^l}{\partial \xi^j} \frac{\partial \xi^m}{\partial x^l} \frac{\partial \xi^i}{\partial x^i} + J \left[\frac{\partial}{\partial x^i} \left(\frac{\partial^2 \xi^j}{\partial x^k} \frac{\partial x^k}{\partial \xi^i} \right) - \frac{\partial \xi^j}{\partial x^k} \frac{\partial^2 x^k}{\partial \xi^i \partial \xi^m} \frac{\partial \xi^m}{\partial x^i} \right]$

$= 0$

Conservation Law:

$$D \cdot A = 0 \quad \frac{\partial A^i}{\partial x^i} = 0 \Rightarrow \frac{\partial A^i}{\partial \xi^j} \frac{\partial \xi^j}{\partial x^i} = 0$$

$$\therefore \frac{\partial}{\partial \xi^j} \left(J \frac{\partial \xi^j}{\partial x^i} \right) = 0$$

$$\text{def: } \bar{A}^j = A^i \frac{\partial \xi^j}{\partial x^i} \quad (\text{recall that } A = \bar{A}^1 x_1 + \dots + \bar{A}^n x_n)$$

$$\therefore A^i = \bar{A}^j \frac{\partial x^i}{\partial \xi^j}$$

$$\therefore A^i \frac{\partial}{\partial \xi^j} \left(J \frac{\partial \xi^j}{\partial x^i} \right) + J \frac{\partial A^i}{\partial \xi^j} \frac{\partial \xi^j}{\partial x^i} = 0$$

$$\Downarrow$$

$$\frac{\partial}{\partial \xi^j} (J \bar{A}^j) = 0$$

$$\text{if } \frac{\partial A^i}{\partial x^i} = F, \text{ then } \frac{1}{J} \frac{\partial}{\partial \xi^j} (J \bar{A}^j) = F$$

$$\frac{\partial A^i}{\partial x^i} = F^i$$

assume A^i is a tensor, so $\bar{A}^j = A^{mn} \frac{\partial \xi^j}{\partial x^m} \frac{\partial \xi^j}{\partial x^n}$

$$\therefore \frac{\partial}{\partial x^i} \left(\bar{A}^{mn} \frac{\partial x^i}{\partial \xi^m} \frac{\partial x^i}{\partial \xi^n} \right) =$$

$$= \frac{\partial \bar{A}^{mn}}{\partial \xi^k} \frac{\partial x^i}{\partial \xi^m} + \bar{A}^{mn} \frac{\partial^2 x^i}{\partial \xi^m \partial \xi^n} + \bar{A}^{mn} \frac{\partial x^i}{\partial \xi^m} \frac{\partial^2 x^i}{\partial \xi^n \partial \xi^k} \frac{\partial \xi^k}{\partial x^i}$$

$$= \frac{\partial \bar{A}^{mn}}{\partial \xi^k} \frac{\partial x^i}{\partial \xi^m} + \bar{A}^{mn} \frac{\partial^2 x^i}{\partial \xi^m \partial \xi^n} + \frac{1}{J} \bar{A}^{mn} \frac{\partial J}{\partial \xi^k} \frac{\partial x^i}{\partial \xi^m} = F^i$$

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$$\therefore \frac{\partial \bar{A}^{pn}}{\partial \xi^m} + \bar{A}^{mn} \frac{\partial x^i}{\partial \xi^m} \frac{\partial \xi^p}{\partial x^i} + \frac{1}{J} \bar{A}^{pn} \frac{\partial J}{\partial \xi^m} = F^i \frac{\partial \xi^p}{\partial x^i} = \bar{F}^p$$

$$\frac{1}{J} \frac{\partial}{\partial \xi^m} (\bar{A}^{pn} J) + P_{mn}^p \bar{A}^{mn} = \bar{F}^p$$

Time - dependent

$$+ \bar{A}^{mn} x_{\xi^m}^n$$

$$\text{let } \xi^0 = \tau$$

$$x^0 = t$$

$$t = \tau$$

the flow velocity $w = \bar{w}^i x_{\xi^i}^i$

$$\bar{w}^i = w \cdot \delta^i_0 = w^j \frac{\partial \xi^i}{\partial x^j} = \frac{\partial x^i}{\partial \tau} \frac{\partial \xi^i}{\partial x^j}$$

$$w^i = \bar{w}^j \frac{\partial x^i}{\partial \xi^j}$$

$$\therefore \frac{\partial \xi^i}{\partial \xi^0} = 0$$

$$\therefore \frac{\partial \xi^i}{\partial x^0} \frac{\partial x^0}{\partial \xi^0} + \frac{\partial \xi^i}{\partial x^j} \frac{\partial x^j}{\partial \xi^0} = 0$$

$$\therefore \frac{\partial \xi^i}{\partial \tau} = - \frac{\partial x^j}{\partial \tau} \frac{\partial \xi^i}{\partial x^j} = - \bar{w}^i$$

$$\frac{1}{J} \frac{\partial}{\partial \tau} (J) = \frac{\partial^2 x^k}{\partial \xi^m \partial \tau} \frac{\partial \xi^m}{\partial x^k} = \frac{\partial}{\partial \xi^m} \left(\bar{w}^j \frac{\partial x^k}{\partial \xi^j} \right) \frac{\partial \xi^m}{\partial x^k}$$

$$= \frac{\partial \bar{w}^m}{\partial \xi^m} + \frac{1}{J} \bar{w}^j \frac{\partial J}{\partial \xi^j} \quad j=1, \dots, n$$

$$= \frac{1}{J} \frac{\partial}{\partial \xi^0} (J \bar{w}^i)$$

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$$d\vec{r} = \frac{d\vec{r}}{d\zeta^i} d\zeta^i$$

let e_{ζ^i} be unit vector along $\frac{d\vec{r}}{d\zeta^i}$

$$\therefore d\vec{r} = \left| \frac{d\vec{r}}{d\zeta^i} \right| d\zeta^i e_{\zeta^i} = h_{\zeta^i} d\zeta^i e_{\zeta^i}$$

$$dl = \sqrt{dr^2} = \sqrt{h_{\zeta^i}^2 d\zeta^i^2}$$

for a scalar function f ,

$$df = \nabla f \cdot d\vec{r}$$

$$= \frac{\partial f}{\partial \zeta^i} d\zeta^i$$

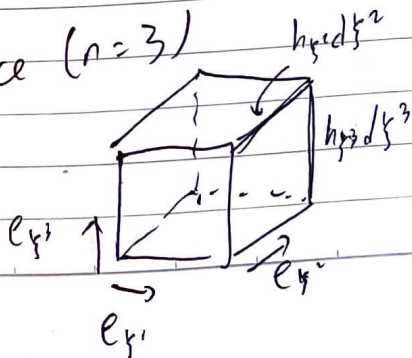
$$= \frac{\partial f}{\partial \zeta^i} \left(\frac{1}{h_{\zeta^i}} d\vec{r} \cdot e_{\zeta^i} \right)$$

$$= \left(\frac{1}{h_{\zeta^i}} \frac{\partial f}{\partial \zeta^i} e_{\zeta^i} \right) \cdot d\vec{r}$$

$$= \nabla f \cdot d\vec{r}$$

$$\therefore \nabla f = \frac{1}{h_{\zeta^i}} \frac{\partial f}{\partial \zeta^i} e_{\zeta^i}$$

Divergence ($n=3$)



for surfaces perpendicular to e_{ζ^1}
area = $h_{\zeta^2} h_{\zeta^3} d\zeta^2 d\zeta^3$

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$$\therefore \frac{d f_1}{d s^1} d s^1 = \frac{d}{d s^1} (f_{s^1} h_{s^1} h_{s^2}) d s^1 d s^2 d s^3$$

Similarly for e_{s^2} , e_{s^3} , so

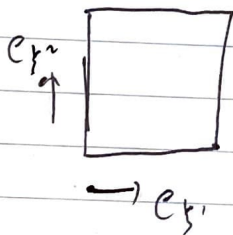
$$0 \cdot \vec{f} = \lim_{\Delta V \rightarrow 0} \frac{1}{\Delta V} \oint \vec{f} \cdot \hat{n} ds$$

$$= \lim_{\Delta V \rightarrow 0} \frac{1}{h_{s^1} h_{s^2} h_{s^3}} \left(\frac{d}{d s^1} (f_{s^1} h_{s^1} h_{s^2}) + \frac{d}{d s^2} (f_{s^2} h_{s^1} h_{s^2}) \right. \\ \left. + \frac{d}{d s^3} (f_{s^3} h_{s^1} h_{s^2}) \right)$$

$$= \frac{1}{h_{s^1} h_{s^2} h_{s^3}} \left(\frac{d}{d s^1} (f_{s^1} h_{s^1} h_{s^2}) + \frac{d}{d s^2} (f_{s^2} h_{s^1} h_{s^2}) \right. \\ \left. + \frac{d}{d s^3} (f_{s^3} h_{s^1} h_{s^2}) \right)$$

Curl ($n=3$)

$$\nabla \times \vec{f} = \lim_{\Delta A \rightarrow 0} \frac{1}{\Delta A} \oint \vec{f} \cdot d\vec{r}$$



along e_{s^1} : $f_{s^1} h_{s^1} d s^1 \rightarrow -\frac{d}{d s^2} (f_{s^1} h_{s^1}) d s^1 d s^2$
 along e_{s^2} : $f_{s^2} h_{s^2} d s^2 \rightarrow \frac{d}{d s^1} (f_{s^2} h_{s^2}) d s^1 d s^2$

$$\therefore \text{for 2D, } \nabla \times \vec{f} = \frac{1}{h_{s^1} h_{s^2}} \left(\frac{d}{d s^1} (f_{s^2} h_{s^2}) - \frac{d}{d s^2} (f_{s^1} h_{s^1}) \right)$$

$$\left[f_{s^2} h_{s^2} \left(s^1 - \frac{d s^1}{v} \right) d s^1 - f_{s^1} h_{s^1} \left(s^2 + \frac{d s^2}{v} \right) d s^2 \right] \\ = - \frac{d}{d s^2} (f_{s^1} h_{s^1}) d s^1 d s^2$$

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$$\text{for } 3D, \nabla \times \vec{f} = \frac{1}{h_1 h_2 h_3} \begin{vmatrix} h_1 e_1 & h_2 e_2 & h_3 e_3 \\ \frac{d}{ds^1} & \frac{d}{ds^2} & \frac{d}{ds^3} \\ f_1 h_1 & f_2 h_2 & f_3 h_3 \end{vmatrix}$$

Cylindrical coordinates:

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$z = z$$

$$h_r = \sqrt{\left(\frac{dx}{dr}\right)^2 + \left(\frac{dy}{dr}\right)^2 + \left(\frac{dz}{dr}\right)^2} = 1$$

$$h_\theta = r$$

$$h_z = 1$$

$$\therefore \nabla^2 f = \frac{1}{h_r h_\theta h_z} \left[\frac{d}{dr} \left(h_\theta h_z \frac{1}{h_r} \frac{df}{dr} \right) + \frac{d}{d\theta} \left(h_r h_z \frac{1}{h_\theta} \frac{df}{d\theta} \right) + \frac{d}{dz} \left(h_r h_\theta \frac{1}{h_z} \frac{df}{dz} \right) \right]$$

$$= \frac{1}{r} \left[\frac{d}{dr} \left(r \frac{df}{dr} \right) + \frac{d}{d\theta} \left(\frac{1}{r} \frac{df}{d\theta} \right) + \frac{d}{dz} \left(r \frac{df}{dz} \right) \right]$$

$$= \frac{1}{r} \frac{d}{dr} \left(r \frac{df}{dr} \right) + \frac{1}{r^2} \frac{d^2 f}{d\theta^2} + \frac{df}{dz^2}$$

Spherical coordinates:

$$x = r \cos \phi \sin \theta$$

$$y = r \sin \phi \sin \theta$$

$$z = r \cos \theta$$

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$$h_r = 1$$

$$h_\theta = \sqrt{r^2 \cos^2 \phi \sin^2 \theta + r^2 \sin^2 \phi \cos^2 \theta + r^2 \sin^2 \theta} = r$$

$$h_\phi = \sqrt{r^2 \sin^2 \phi \sin^2 \theta + r^2 \cos^2 \phi \sin^2 \theta + 0} = r \sin \theta$$

$$\begin{aligned} \therefore \nabla^2 f &= \frac{1}{r^2 \sin \theta} \left[\frac{d}{dr} \left(r^2 \sin \theta \frac{df}{dr} \right) + \frac{d}{d\theta} \left(\sin \theta \frac{df}{d\theta} \right) + \frac{d}{d\phi} \left(\frac{1}{\sin \theta} \frac{df}{d\phi} \right) \right] \\ &= \frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{df}{dr} \right) + \frac{1}{r^2 \sin \theta} \frac{d}{d\theta} \left(\sin \theta \frac{df}{d\theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{d^2 f}{d\phi^2} \end{aligned}$$

(note)

$$\frac{\partial A^i}{\partial x^i} \text{ etc} = \frac{1}{J} \left[J \frac{\partial A^i}{\partial x^i} \frac{\partial x^j}{\partial x^i} + A^i \frac{d}{dx^j} \left(J \frac{\partial x^j}{\partial x^i} \right) \right]$$

$$= \frac{1}{J} \left[\frac{d}{dx^j} \left(J A^i \frac{\partial x^j}{\partial x^i} \right) \right]$$

$$= \frac{1}{J} \frac{d}{dx^j} \left(J A^j \right) = \frac{1}{J} \frac{d}{dx^j} \left(A^i g^{ij} \right)$$

$$A = \bar{A}^i x_{ji} = A_{ci} e_i$$

$$\therefore A_{ci} = h_{ji} A^i$$

$$A^i = \frac{A_{ci}}{h_{ji}}$$

Unit vector (Cylindrical coordinates)

$$e_{\phi 0} = \frac{\partial \vec{r}}{\partial \phi^i} / \left| \frac{\partial \vec{r}}{\partial \phi^i} \right| = \frac{1}{\left| \frac{\partial \vec{r}}{\partial \phi^i} \right|} \left(\frac{\partial x^1}{\partial \phi^i} e_1 + \dots + \frac{\partial x^n}{\partial \phi^i} e_n \right)$$

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$z = z$$

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$$e_r = \cos\theta e_1 + \sin\theta e_2$$

$$e_\theta = (-\sin\theta e_1 + \cos\theta e_2) \frac{1}{r}$$

$$e_x = e_1$$

$$\frac{de_r}{dr} = 0 \quad \frac{de_r}{d\theta} = -\sin\theta e_1 + \cos\theta e_2 = e_\theta \quad \frac{de_r}{dx} = 0$$

$$\frac{de_\theta}{dr} = 0 \quad \frac{de_\theta}{d\theta} = -e_r \quad \frac{de_\theta}{dx} = 0$$

$$\frac{de_x}{dr} = 0 \quad \frac{de_x}{d\theta} = 0 \quad \frac{de_x}{dx} = 1$$

Unit vector (Spherical coordinates)

$$x = r \cos\phi \sin\theta$$

$$y = r \sin\phi \sin\theta$$

$$z = r \cos\theta$$

$$e_r = \cos\phi \sin\theta e_1 + \sin\phi \sin\theta e_2 + \cos\theta e_3$$

$$e_\theta = (r \cos\phi \cos\theta e_1 + r \sin\phi \cos\theta e_2 - r \sin\theta e_3) \frac{1}{r}$$

$$e_\phi = (-r \sin\phi \sin\theta e_1 + r \cos\phi \sin\theta e_2) \frac{1}{r \sin\theta}$$

$$\frac{de_r}{dr} = 0 \quad \frac{de_r}{d\theta} = e_\theta \quad \frac{de_r}{d\phi} = \sin\theta e_\phi \quad \frac{de_r}{dx} = 0 \quad \frac{de_r}{dy} = 0$$

$$\frac{de_\theta}{dr} = 0 \quad \frac{de_\theta}{d\theta} = -e_r \quad \frac{de_\theta}{d\phi} = \cos\theta e_\phi \quad \frac{de_\theta}{dx} = -\cos\phi e_1 - \sin\phi e_2$$

$$\frac{de_\theta}{dy} = -\sin\phi e_1 + \cos\phi e_2$$

$$\begin{aligned}
 e_i \frac{dA}{dx^i} &= e_i \frac{dA}{dx^j} \frac{dx^j}{dx^i} \\
 &= \chi_{ye} \frac{dx^e}{dx^i} \frac{dx^j}{dx^i} \frac{dA}{dx^j} \\
 &= \chi_{ye} g^{ej} \frac{dA}{dx^j} \\
 &= \chi_{ye} g^{ej} \frac{dA}{dx^j} \hat{\chi}_{ye}
 \end{aligned}$$

if orthogonal, $g^{ij} = g^{ji} \delta^i_j$, $g^{ii} = \frac{1}{g_{ii}} = \frac{1}{h_{ji}^2}$

$$\therefore e_i \frac{dA}{dx^i} = \frac{1}{h_{ye}} \frac{dA}{dx^j} \hat{\chi}_{ye}$$

∇A

let C be a curve, tangent is given by:

$$\tau = \frac{dx}{ds} = \frac{dx}{dx^i} \frac{dx^i}{ds} = \frac{dx^j}{ds} \chi_{ji} = \tau^j \chi_{ji}$$

$$\begin{aligned}
 \nabla A \cdot \tau &= \frac{dA}{ds} = \left(\frac{dA}{dx^i} \frac{dx^i}{dx} \right) \cdot (\tau^j \chi_{ji}) \\
 &= \left(\frac{dA}{dx^i} \chi_{ji} \right) \cdot (\tau^j \chi_{ji})
 \end{aligned}$$

recall that $\chi_{ji} \cdot \chi^{ji} = \delta^j_j$

\therefore we can define ∇ as ~~$\frac{dA}{dx^i} \chi_{ji}$~~ $\chi^{ji} \frac{dA}{dx^i}$

$\nabla \vec{A}$

~~$$\nabla \vec{A} = \nabla_j A_i = x^{ji} \frac{\partial A_i}{\partial x^j}$$~~

$$\nabla \vec{A} = x^{ji} \frac{\partial \vec{A}}{\partial x^j} = x^{ji} \frac{d}{dx^j} (A^i x_{ji})$$

$$= x^{ji} \left[\frac{\partial A^i}{\partial x^j} x_{ji} + A^i x_{ji;j} \right]$$

$$= x^{ji} \left[\frac{\partial A^i}{\partial x^j} x_{ji} + A^i \Gamma_{ij}^k x_{jk} \right]$$

$$= x^{ji} A^i |_{,j} x_{ji}$$

$$= A^i |_{,j} x^{ji} x_{ji}$$

$$\therefore x^{ji} = \frac{d}{dx^j} \left(\frac{dx^i}{dx} \right) = \frac{\partial x^i}{\partial x^k \partial x} \frac{dx^k}{dx^j} = - \frac{\partial x^i}{\partial x^k} \frac{\partial x^k}{\partial x^m \partial x^j} \frac{dx^m}{dx} = -\Gamma_{mj}^i x^{sm} = -\Gamma_{jm}^i x^{sm}$$

$$\therefore \nabla \vec{A} = x^{ji} \frac{d}{dx^j} (\cancel{A_i} x^{ji})$$

$$= x^{ji} \left(\frac{\partial A_i}{\partial x^j} x^{ji} + A_i x^{ji;j} \right)$$

$$= x^{ji} \left(\frac{\partial A_i}{\partial x^j} x^{ji} - A_i \Gamma_{jk}^i x^{jk} \right)$$

$$= A_i |_{,j} x^{ji} x^{ji}$$

$\nabla^2 A$

$$\begin{aligned} \nabla^2 A &= x^{jk} \frac{\partial}{\partial x^k} (A^{ij} x_{ji} x_{ji}) = x^{jk} \left[\frac{\partial A^{ij}}{\partial x^k} x_{ji} x_{ji} + A^{ij} \Gamma_{ik}^m x_{jm} x_{ji} + A^{ij} \Gamma_{kj}^n x_{ji} x_{in} \right] \\ &= \left(\frac{\partial A^{ij}}{\partial x^k} + A^{mj} \Gamma_{mk}^i + A^{in} \Gamma_{kn}^j \right) x_{ji} x_{ji} x^{jk} \end{aligned}$$

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$$= A^{ij} |_{,k} x_{y^i} x_{y^j} x^{y^k}$$

$D \cdot \vec{A}$

$$D \cdot \vec{A} = D \vec{A} \cdot \vec{I} = A^i |_{,i} x^{y^i} x_{y^i}$$

$D \cdot \vec{A}^2$

$$D \cdot \vec{A}^2 = D \vec{A}^2 \cdot \vec{I} = A^{ij} |_{,i} x_{y^i} x_{y^j} x^{y^i}$$

$D \times \vec{A}$

$$D \times \vec{A} = x^{y^j} \times \frac{\partial \vec{A}}{\partial y^j} = x^{y^j} \times \frac{\partial}{\partial y^j} (A^i x_{y^i})$$

$$= x^{y^j} \times x_{y^i} \frac{\partial A^i}{\partial y^j} + A^i x^{y^j} x_{y^i} |_{,j}$$

$$= \frac{\partial A^i}{\partial y^j} x^{y^j} \times x_{y^i} + A^i \Gamma_{ij}^k x_{y^k}$$

$$= A^i |_{,j} x^{y^j} \times x_{y^i} \quad \text{note that } \frac{\partial A^i}{\partial y^j} - \frac{\partial A^j}{\partial y^i}$$

is not a tensor

$$D \times \vec{A} = x^{y^j} \times \frac{\partial}{\partial y^j} (A^i x_{y^i}) = x^{y^j} \times x_{y^i} \left(\frac{\partial A^i}{\partial y^j} - A^k \Gamma_{ij}^k \right)$$

note that, for example, $(D \times \vec{A})_r = x^i x^o \left(\frac{\partial A^o}{\partial r} - \frac{\partial A^r}{\partial o} + A_k \Gamma_{ro}^k - A_k \Gamma_{or}^k \right)$

a tensor, however it's not the usual one because it has two indices.

$$\therefore D \times \vec{A} \equiv \epsilon^{ijk} D_i A_j = \frac{\epsilon^{ijk}}{\sqrt{g}} D_i A_j$$

Geometry (differential)

No.

Date. 17.10.2017

$$x_{\gamma^i} = \frac{\partial x}{\partial \gamma^i} \quad g^{ij} g_{jlc} = \frac{\partial \gamma^i}{\partial x^m} \frac{\partial \gamma^j}{\partial x^m} \frac{\partial x^m}{\partial \gamma^j} \frac{\partial x^m}{\partial \gamma^c} = \frac{\partial \gamma^i}{\partial x^m} \frac{\partial x^m}{\partial \gamma^c} = \delta^i_c$$

$$x_{\gamma^i} g^{ij} = \frac{\partial x^m}{\partial \gamma^i} \frac{\partial \gamma^j}{\partial x^m} \frac{\partial \gamma^j}{\partial x^m} = \sum_m \frac{\partial \gamma^j}{\partial x^m} \frac{\partial \gamma^j}{\partial x^m} = \frac{\partial \gamma^j}{\partial x^m} = \chi^{\gamma^j}$$

$$\chi^{\gamma^i} g_{ij} = \frac{\partial \gamma^i}{\partial x^m} \frac{\partial x^m}{\partial \gamma^i} \frac{\partial x^m}{\partial \gamma^j} = \sum_m \frac{\partial x^m}{\partial \gamma^j} = \chi_{\gamma^j}$$

physical quantity $A_{(i)}$, $A = A_{(i)} e_{(i)}$

$$A = A^i x_{\gamma^i} = A_i \chi^{\gamma^i}$$

$$= A^i h_{\gamma^i} e_{\gamma^i} = A_i \frac{1}{h_{\gamma^i}} e^{\gamma^i} = A_{(i)} e_{(i)}$$

$$\therefore A^i = \frac{A_{(i)}}{h_{\gamma^i}} \quad A_i = h_{\gamma^i} A_{(i)}$$

Orthogonal coordinates

$$x_{\gamma^i} \cdot x_{\gamma^j} = h_{ij}^2 \delta_{ij} \Rightarrow g_{ij} = g^{ij} = 0 \text{ if } i \neq j$$

~~$$r^i_{jk} = g^{im} \frac{\partial x_{\gamma^j}}{\partial \gamma^i} \frac{\partial x_{\gamma^k}}{\partial \gamma^m} = \frac{\partial x_{\gamma^j}}{\partial \gamma^i} \frac{\partial x_{\gamma^k}}{\partial \gamma^i} = \chi_{\gamma^j} \chi_{\gamma^k}$$~~

$$r^i_{jk} = \frac{1}{2} g^{im} \left(\frac{\partial g_{jm}}{\partial \gamma^i} + \frac{\partial g_{im}}{\partial \gamma^j} - \frac{\partial g_{jk}}{\partial \gamma^m} \right)$$

if $i \neq j \neq k$, each term is obviously zero

$$\therefore r^i_{jk} = 0 \text{ when } i \neq j \neq k$$

from property of Christoffel's symbol,

$$\Gamma_{jk}^i = \Gamma_{kj}^i$$

$$\Gamma_{ij}^i = \Gamma_{ji}^i = \frac{1}{2} g^{im} \left(\frac{\partial g_{im}}{\partial x^j} + \frac{\partial g_{jm}}{\partial x^i} - \frac{\partial g_{ij}}{\partial x^m} \right) \quad i \neq j$$

$$= \frac{1}{2} g^{ii} \left(\frac{\partial g_{ii}}{\partial x^j} + \frac{\partial g_{ji}}{\partial x^i} \right)$$

$$= \frac{1}{2} g^{ii} \frac{\partial g_{ii}}{\partial x^j}$$

$$\Gamma_{jj}^i = -\frac{1}{2} g^{ii} \frac{\partial g_{jj}}{\partial x^i} \quad \therefore \Gamma_{ii}^i = \frac{1}{2} g^{ii} \frac{\partial g_{ii}}{\partial x^i}$$

Cylindrical coordinates

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$z = z$$

$$(x, y, z) \rightarrow (r, \theta, z)$$

$$g_{rr} = \frac{\partial x}{\partial r} \cdot \frac{\partial x}{\partial r} = \cos^2 \theta + \sin^2 \theta = 1$$

[the unit vector (4/10/2017)]

$$g_{\theta\theta} = \frac{\partial x}{\partial \theta} \cdot \frac{\partial x}{\partial \theta} = r^2 (\cos^2 \theta + \sin^2 \theta) = r^2$$

$$g_{zz} = 1$$

$$\Gamma_{rr}^r = \frac{1}{2} g^{rr} \frac{\partial g_{rr}}{\partial r} = 0$$

$$\Gamma_{r\theta}^r = \Gamma_{\theta r}^r = \Gamma_{rz}^r = \Gamma_{zr}^r = 0$$

$$\Gamma_{\theta\theta}^{\theta} = \frac{1}{2} g^{\theta\theta} \frac{\partial g_{\theta\theta}}{\partial \theta} = 0$$

$$\Gamma_{r\theta}^{\theta} = \Gamma_{\theta r}^{\theta} = \frac{1}{2} g^{\theta\theta} \frac{\partial g_{\theta\theta}}{\partial r} = \frac{1}{2r^2} \cdot 2r = \frac{1}{r}$$

$$\Gamma_{zz}^z = 0$$

$$\Gamma_{r\theta}^z = \Gamma_{\theta r}^z = 0$$

Geometry (Differential)

No.

Date. 17.10.2017

$$\Gamma_{rz}^z = \Gamma_{zr}^z = \Gamma_{oz}^z = \Gamma_{zo}^z = 0$$

$$\Gamma_{\theta\theta}^r = -\frac{1}{2} g^{rr} \frac{dg_{\theta\theta}}{dr} = -r \quad \Gamma_{z\theta}^r = 0$$

$$\Gamma_{rr}^o = \Gamma_{zz}^o = 0$$

$$\Gamma_{rr}^z = 0 \quad \Gamma_{\theta\theta}^z = -\frac{1}{2} g^{zz} \frac{dg_{\theta\theta}}{dz} = 0$$

Spherical coordinates

$$x = r \cos\phi \sin\theta$$

$$y = r \sin\phi \sin\theta$$

$$z = r \cos\theta$$

$$g_{rr} = \frac{\partial \vec{x}}{\partial r} \cdot \frac{\partial \vec{x}}{\partial r} = 1$$

[See Unit Vector 4/10/2017]

$$g_{\theta\theta} = \frac{\partial \vec{x}}{\partial \theta} \cdot \frac{\partial \vec{x}}{\partial \theta} = r^2$$

$$g_{\phi\phi} = \frac{\partial \vec{x}}{\partial \phi} \cdot \frac{\partial \vec{x}}{\partial \phi} = r^2 \sin^2\theta$$

$$\Gamma_{rr}^r = 0 \quad \Gamma_{r\theta}^r = \Gamma_{\theta r}^r = \Gamma_{r\phi}^r = \Gamma_{\phi r}^r = 0$$

$$\Gamma_{\theta\theta}^o = 0 \quad \Gamma_{r\theta}^o = \Gamma_{\theta r}^o = \frac{1}{2} g^{oo} \frac{dg_{\theta\theta}}{dr} = \frac{1}{2r^2} \cdot 2r = \frac{1}{r}$$

$$\Gamma_{\phi\phi}^o = 0 \quad \Gamma_{\phi\theta}^o = \Gamma_{\theta\phi}^o = 0$$

$$\Gamma_{\theta\theta}^r = -\frac{1}{2} g^{rr} \frac{dg_{\theta\theta}}{dr} = -r \quad \Gamma_{r\phi}^r = \Gamma_{\phi r}^r = \frac{1}{2} g^{r\phi} \frac{dg_{\phi\phi}}{dr} = \frac{1}{r \sin^2\theta} \cdot 2r \sin^2\theta = \frac{1}{r}$$

$$\Gamma_{\phi\phi}^r = -\frac{1}{2} g^{rr} \frac{dg_{\phi\phi}}{dr} = -r \sin^2\theta \quad \Gamma_{\theta\phi}^r = \Gamma_{\phi\theta}^r = \frac{1}{2} g^{r\phi} \frac{dg_{\phi\phi}}{d\theta} = \frac{1}{2r \sin^2\theta} \cdot 2r^2 \sin\theta \cos\theta$$

$$\Gamma_{rr}^o = 0 \quad = \cot\theta$$

$$\Gamma_{\phi\phi}^0 = -\frac{1}{2} g^{00} \frac{\partial g_{\phi\phi}}{\partial \theta} = -\frac{1}{2r^2} \cdot 2r^2 \sin\theta \cos\theta = \cancel{\frac{1}{2r^2}} - \frac{\sin 2\theta}{2}$$

$$\Gamma_{\phi r}^{\phi} = 0$$

$$\Gamma_{00}^{\phi} = -\frac{1}{2} g^{\phi\phi} \frac{\partial g_{00}}{\partial \phi} = 0$$

Examples: (Spherical coordinates) $[v^r = v_r, v^\theta = \frac{v_\theta}{r}, v^\phi = \frac{v_\phi}{r \sin\theta}]$

$$\vec{0} \cdot \vec{v} = \chi_{\phi}^{j_i} \frac{\partial}{\partial y^j} (v^i \chi_{\phi}^i) = A^i |_{\phi} \chi_{\phi}^i \cdot \chi_{\phi}^i = A^i |_{\phi} = \frac{\partial A^i}{\partial y^j} + A^j |_{\phi}^i$$

$$= \frac{\partial v_r}{\partial r} + \frac{\partial v_\theta}{\partial \theta} + \frac{\partial v_\phi}{\partial \phi} + v^r \cdot \frac{1}{r} + v^\theta \frac{1}{r} + v^\phi \cot\theta$$

$$= \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_r) + \frac{1}{r \sin\theta} \frac{\partial}{\partial \theta} (\sin\theta v_\theta) + \frac{1}{r \sin\theta} \frac{\partial v_\phi}{\partial \phi}$$

$$\vec{v} \cdot \nabla \vec{v} = v^i \chi_{\phi}^i \chi_{\phi}^{j_i} \frac{\partial}{\partial y^j} (v^j \chi_{\phi}^j) = A^i A^j |_{\phi} \chi_{\phi}^i \cdot \chi_{\phi}^j \cdot \chi_{\phi}^j$$

$$= v^i \left(\frac{\partial v^j}{\partial y^i} + v^k |_{\phi}^j \right) \chi_{\phi}^j$$

if $j=1$

$$(\vec{v} \cdot \nabla \vec{v})_r = v^r \frac{\partial v_r}{\partial r} + v^\theta \frac{\partial v_r}{\partial \theta} + v^\phi \frac{\partial v_r}{\partial \phi} + v^\theta \left(\frac{1}{r} \right) + v^\phi \left(\frac{1}{r} \right)$$

$$= v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} + \frac{v_\phi}{r \sin\theta} \frac{\partial v_r}{\partial \phi} - \frac{v_\theta^2 + v_\phi^2}{r}$$

if $j=2$

$$(\vec{v} \cdot \nabla \vec{v})_\theta = \left[v^r \frac{\partial v_\theta}{\partial r} + v^\theta \frac{\partial v_\theta}{\partial \theta} + v^\phi \frac{\partial v_\theta}{\partial \phi} + 2v^r v^\theta \left(\frac{1}{r} \right) + v^\phi \left(-\sin\theta \cos\theta \right) \right] \cdot r$$

$$= \left[v_r \frac{\partial}{\partial r} \left(\frac{v_\theta}{r} \right) + \frac{v_\theta}{r^2} \frac{\partial v_\theta}{\partial \theta} + \frac{v_\phi}{r \sin\theta} \frac{\partial v_\theta}{\partial \phi} + 2 \frac{v_r v_\theta}{r} - \frac{v_\theta^2}{r^2} \cot\theta \right] \cdot r$$

$$= v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_\phi}{r \sin\theta} \frac{\partial v_\theta}{\partial \phi} + \frac{v_r v_\theta}{r} - \frac{v_\theta^2}{r} \cot\theta$$

if $j=3$

$$(\vec{v} \cdot \nabla \vec{v})_\phi = \left[v^r \frac{\partial v_\phi}{\partial r} + v^\theta \frac{\partial v_\phi}{\partial \theta} + v^\phi \frac{\partial v_\phi}{\partial \phi} + 2v^r v^\phi \left(\frac{1}{r} \right) + 2v^\theta v^\phi \left(\frac{\cot\theta}{r} \right) \right] r \sin\theta$$

=

Geometry (differential)

19/10/2017

$$\nabla \cdot \vec{v} = \nabla \cdot (\nabla \vec{v} + (\nabla \vec{v})^T)$$

$$\nabla \vec{v} = \chi^{s_i} \frac{\partial}{\partial x^s} (v^i \chi_{s_i}) = \left(\frac{\partial A^i}{\partial x^s} + A^k \Gamma_{kj}^i \right) \chi^{s_j} \chi_{s_i} = A^i |_{,j} \chi^{s_j} \chi_{s_i}$$

$$(\nabla \vec{v})_{,r} = \frac{\partial v^r}{\partial r} = \frac{\partial v_r}{\partial r}$$

$$(\nabla \vec{v})_{r\theta} = \left[\frac{\partial v^r}{\partial \theta} + v^\theta (-r) \right] \frac{1}{r} = \frac{1}{r} \frac{\partial v_r}{\partial \theta} - \frac{v_\theta}{r}$$

$$(\nabla \vec{v})_{\theta r} = \left[\frac{\partial v^\theta}{\partial r} + v^r \frac{1}{r} \right] \cdot r = r \frac{\partial}{\partial r} \left(\frac{v_\theta}{r} \right) + \frac{v_\theta}{r}$$

$$(\nabla \vec{v})_{,\phi} = \left[\frac{\partial v^r}{\partial \phi} + v^\theta (-r \sin^2 \theta) \right] \frac{1}{r \sin \theta} = \frac{1}{r \sin \theta} \frac{\partial v_r}{\partial \phi} - \frac{v_\theta}{r} \cot \theta$$

$$(\nabla \vec{v})_{\phi r} = \left[\frac{\partial v^\phi}{\partial r} + v^r \left(\frac{1}{r} \right) \right] r \sin \theta = r \frac{\partial}{\partial r} \left(\frac{v_\phi}{r} \right) + \frac{v_\phi}{r}$$

$$(\nabla \vec{v})_{\theta\theta} = \left[\frac{\partial v^\theta}{\partial \theta} + v^r \frac{1}{r} \right] = \frac{1}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r}{r}$$

$$(\nabla \vec{v})_{\theta\phi} = \left[\frac{\partial v^\theta}{\partial \phi} - v^r (-r \sin \theta \cos \theta) \right] \frac{1}{r \sin \theta} = \frac{1}{\sin \theta} \frac{\partial}{\partial \phi} \left(\frac{v_\theta}{r} \right) - \frac{v_\phi}{r} \cot \theta$$

$$(\nabla \vec{v})_{\phi\theta} = \left[\frac{\partial v^\phi}{\partial \theta} + v^r \cot \theta \right] \frac{1}{r} r \sin \theta = \frac{\sin \theta}{r} \frac{\partial}{\partial \theta} \left(\frac{v_\phi}{\sin \theta} \right) + \frac{v_\phi}{r} \cot \theta$$

$$(\nabla \vec{v})_{\phi\phi} = \left[\frac{\partial v^\phi}{\partial \phi} + v^r \left(\frac{1}{r} \right) + v^\theta \cot \theta \right] = \frac{1}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi} + \frac{v_r}{r} + \frac{v_\theta}{r} \cot \theta$$

$$\nabla \cdot \nabla \vec{v} = \left(\frac{\partial A^i |_{,j}}{\partial x^j} + A^k |_{,j} \Gamma_{jk}^i - A^i |_{,k} \Gamma_{ij}^k \right) \chi^{s_j} \chi^{s_i} \chi_{s_i}$$

extra

$$\tilde{\epsilon}^{ijk} \frac{\partial x^p}{\partial x^i} \frac{\partial x^q}{\partial x^j} \frac{\partial x^r}{\partial x^k} = \frac{\tilde{\epsilon}^{ijk}}{\sqrt{g}} \frac{\partial x^p}{\partial x^i} \frac{\partial x^q}{\partial x^j} \frac{\partial x^r}{\partial x^k} = \frac{\epsilon^{pqr}}{\sqrt{g}} \sqrt{g} = \frac{\epsilon^{pqr}}{\sqrt{g}} = \epsilon^{pqr}$$

$$\sqrt{J} = \sqrt{\frac{g}{g}} = \begin{vmatrix} \frac{\partial x^1}{\partial x^1} & \frac{\partial x^1}{\partial x^2} \\ \frac{\partial x^2}{\partial x^1} & \frac{\partial x^2}{\partial x^2} \end{vmatrix}$$